



# 7<sup>TH</sup> ESTAD



**ASSOCIAZIONE  
ITALIANA DI  
METALLURGIA**

**EUROPEAN STEEL TECHNOLOGY  
AND APPLICATION DAYS**

VERONA, ITALY

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## **Application of Deep Learning technique to improve the scrap quality**

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## BACKGROUND

Accurate scrap identification is essential to control tramp elements, enhance steel quality, and drive low-carbon, circular steel production.

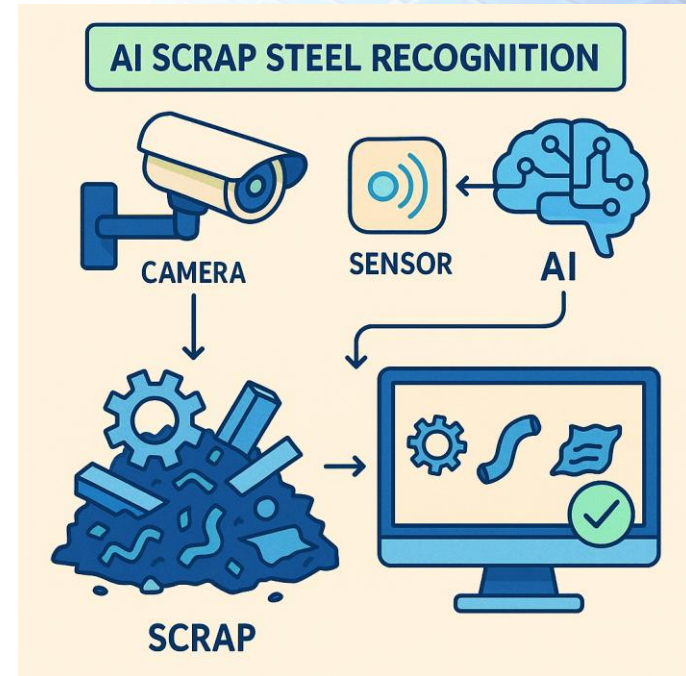


**When uninvited elements  
join the melt...**

When uninvited elements  
join the melt...

## BACKGROUND

The application of DL techniques for scrap task is crucial to enhance scrap recycling technology and exploit the application of AI in metallurgy.

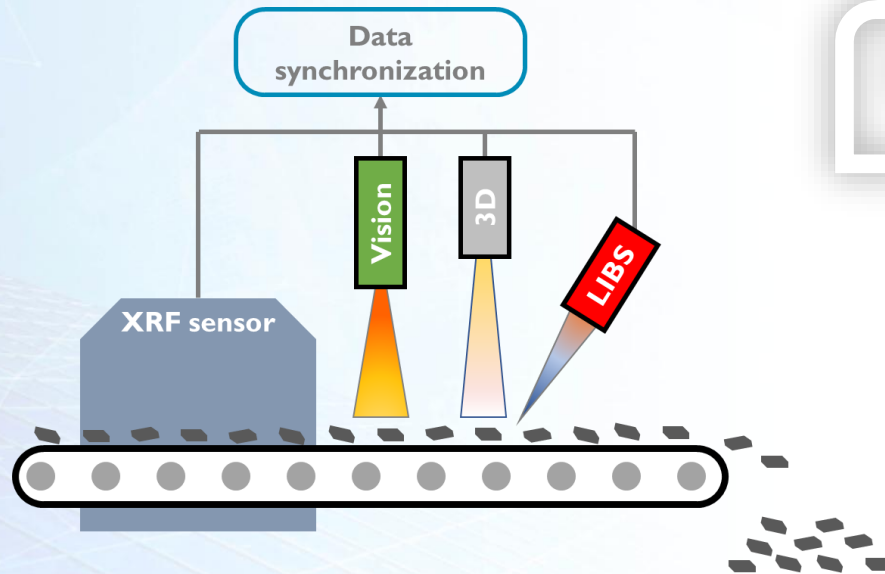


## PURESCRAP - PURity improvement of SCRAP metal”

**Objective:** increase the use of **low-quality scrap** grades by applying the best available technologies to reduce impurities.



# PURESCRAP PROJECT – Shredded line



Provide an integrated set of measuring technologies to increase the average scrap quality for optimising the melting furnace's charge

## **PURESCRAP PROJECT – Test line**



Test Line installed at Stena Recycling  
in Sweden

# 2D CAMERA – Automatic detection and identification of copper



Images collected during  
the experimental tests

Development and  
evaluation of Deep  
Learning based models



## DATASET

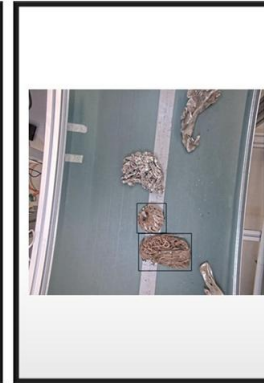
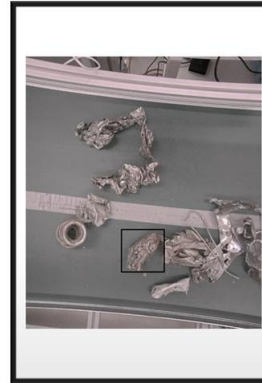
Four datasets were created reflecting successive stages of data collection. Each new version of the dataset was built upon the previous one, gradually increasing the volume and variability of the data (except Dataset 3).

| <i>Dataset</i>   | <b>Total number of images</b> | <b>Total number of ground truth annotations</b> | <b>Annotation per image</b> |
|------------------|-------------------------------|---|-----------------------------|
| <i>Dataset 1</i> | 2330                          | 4220  | 1.81                        |
| <i>Dataset 2</i> | 2798                          | 4818  | 1.72                        |
| <i>Dataset 3</i> | 1877                          | 3959  | 2.11                        |
| <i>Dataset 4</i> | 3394                          | 5665  | 1.67                        |

## LABELLING

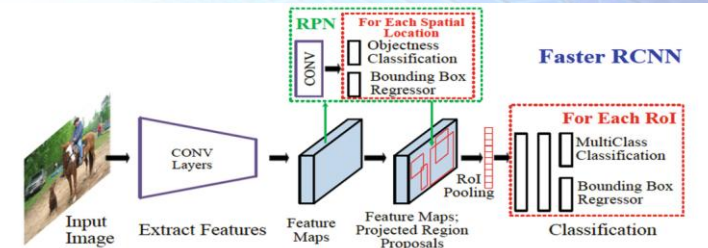
The target object is annotated using a black bounding box.

These annotations serve as ground truth during training and evaluation, enabling the model to learn the spatial and visual characteristics of the object across varying contexts.



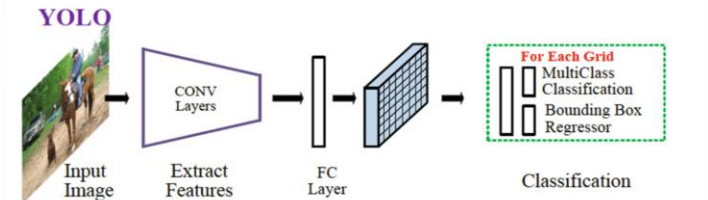
# IMAGE PROCESSING - Copper Detection Models

Model based on the **FasterRCNN** + **ResNetX-101** architecture: ImageNet pre-trained ResNext101 weights as a backbone and Feature Pyramid Network in Faster RCNN as Neck.



<sup>1</sup>Rocha, Á., Adeli, H., Reis, L. P., & Costanzo, S. (Eds.). (2018). Trends and Advances in Information Systems and Technologies: Volume 1

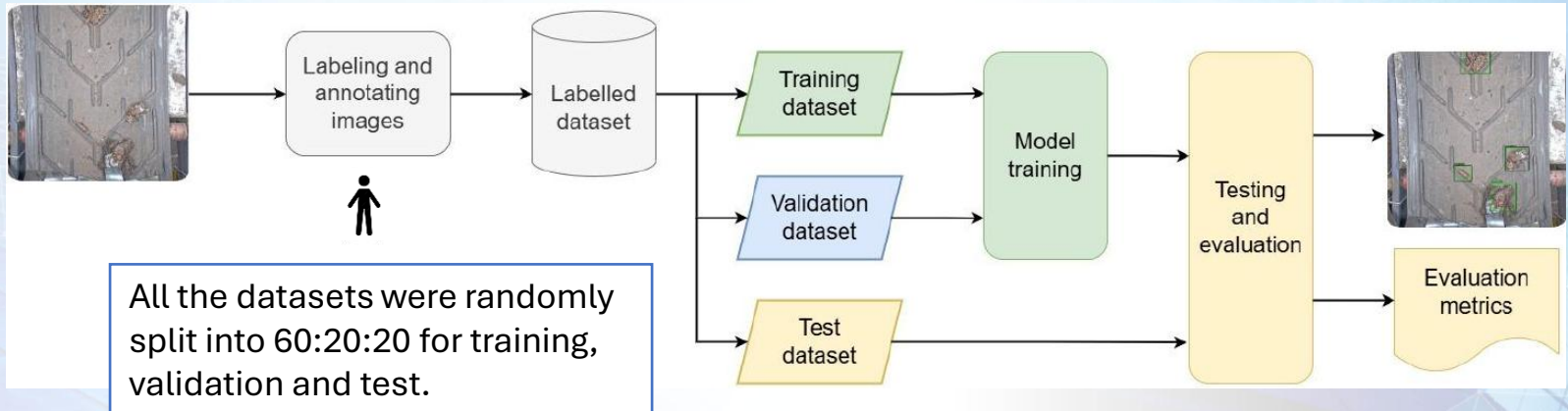
Model based on **YOLO architecture**, one-stage detector proposed by Redmon et al<sup>2</sup>.



<sup>2</sup>Redmon, J.; Divvala, S.; Girshick, R.; Farhadi, A., "You only look once: Unified, real-time object detection", In Proceedings of the IEEE conference on computer vision and pattern recognition, 2016.

# IMAGE PROCESSING - Copper Detection Models

Pipeline for training and evaluating the deep learning-based computer vision models for copper detection tasks. The pipeline is designed to follow a supervised learning approach.



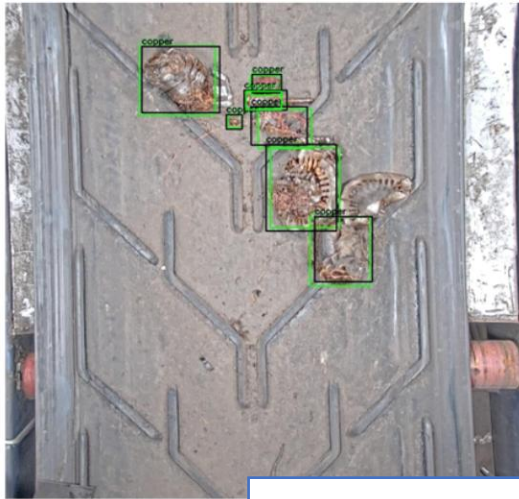
## RESULTS

| Model      | Split      | mAP <sub>50%</sub> | GT   | TP   | FP  | FN | FPS   |
|------------|------------|--------------------|------|------|-----|----|-------|
| FasterRCNN | Validation | 92.66              | 1222 | 1155 | 96  | 67 | 2.51  |
|            | Test       | 91.26              | 1174 | 1096 | 131 | 78 | 2.46  |
| YOLO       | Validation | 92.91              | 1222 | 1152 | 72  | 70 | 11.95 |
|            | Test       | 92.44              | 1174 | 1098 | 99  | 76 | 11.74 |

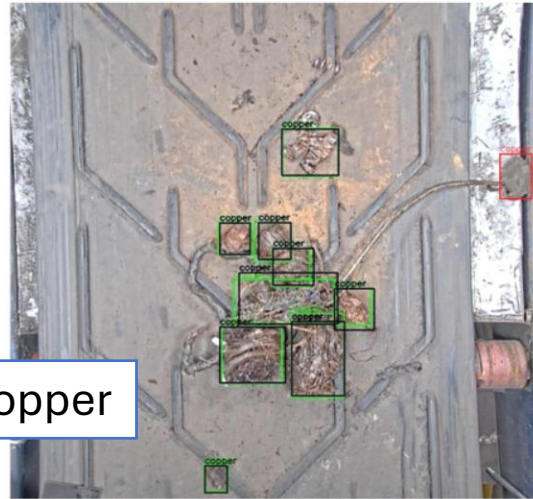
**High-precision (>90% mAP) ready for system integration.**

**Key performance metric for real-time applications.**

## RESULTS



Test with only copper



Real case scenario

## ON GOING WORK

*We are testing the model on the  
process line images*

*Sensor box on the production line*



# FUTURE WORK ON THE PRODUCTION LINE

Synchronization of data

Merge image processing,  
LIBS data and LiDAR data

Development of ML  
model to merge all data



# THANK YOU!

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